



Texture Analysis for Computed Tomography Studies

Stelu Aioanei, Arati Kurani, Dong-Hui Xu
CTI Undergraduates

Advisors: Jacob Furst, PhD, Assistant Professor
Daniela Raicu, PhD, Assistant Professor

CTI, DePaul University

- **Research Interests**

- Data Mining for United States Patent and Trademark Office
- Data Mining for Customer Behavior Modeling
- **Medical Imaging**
 - Collaborators: Department of Radiology, Northwestern Memorial Hospital, Chicago, IL
 - Dr. David Channin, Director of the Department of Radiology
 - Dr. Alice Averbukh, Research Associate

- **Project**

- Classification of Tissues Using Texture Information in CT studies

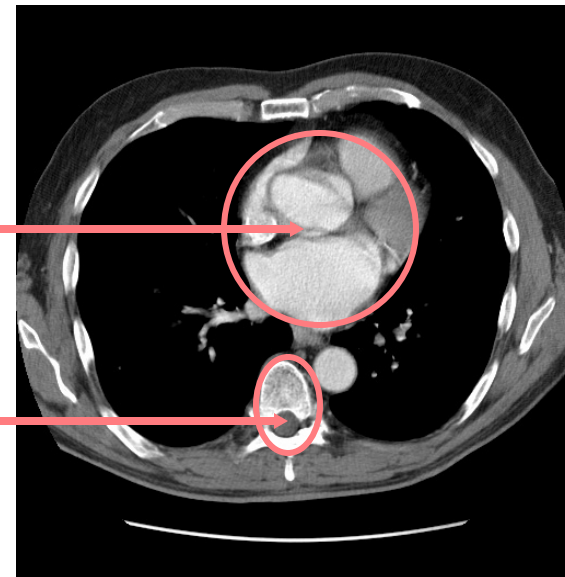
- **Problem Statement**

- The classification of human organs using raw data (pixels) from abdominal and chest CT images
- While traditional texture metrics have concentrated on 2D texture, 3D imaging modalities are becoming more and more prevalent, providing the possibility of examining texture as a volumetric phenomenon
- We expect that texture derived from volumetric data will have better discriminating power than 2D texture derived from slice data, thus increasing the organ classification accuracy

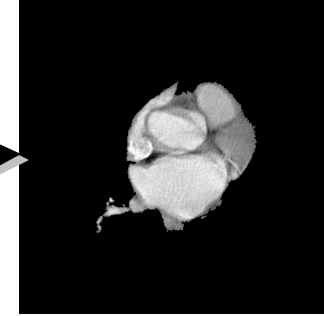
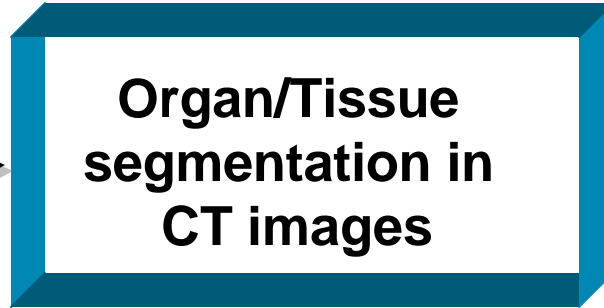
*labels for the organs
present in the image*

heart

backbone

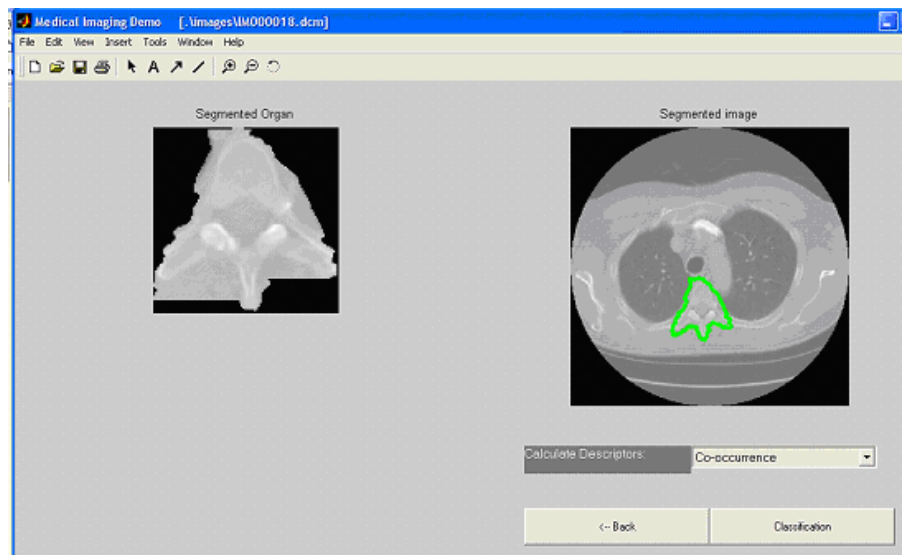
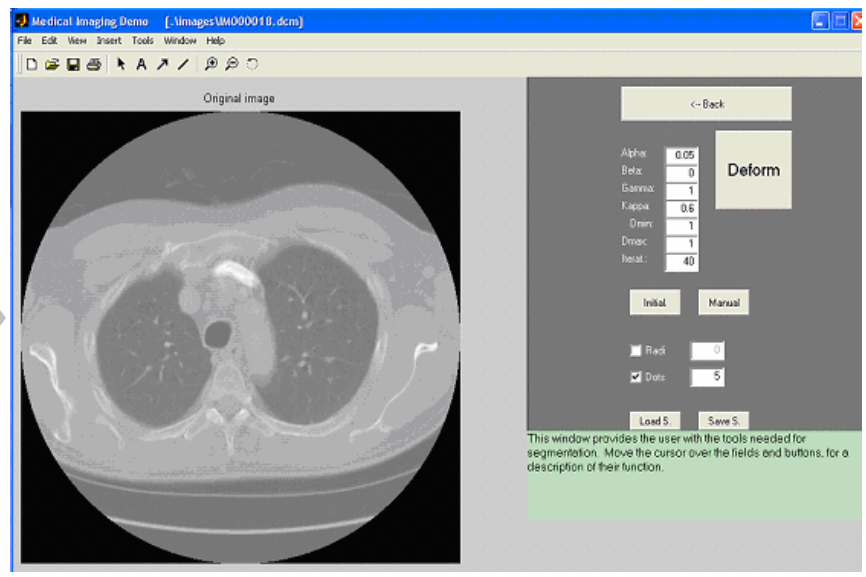
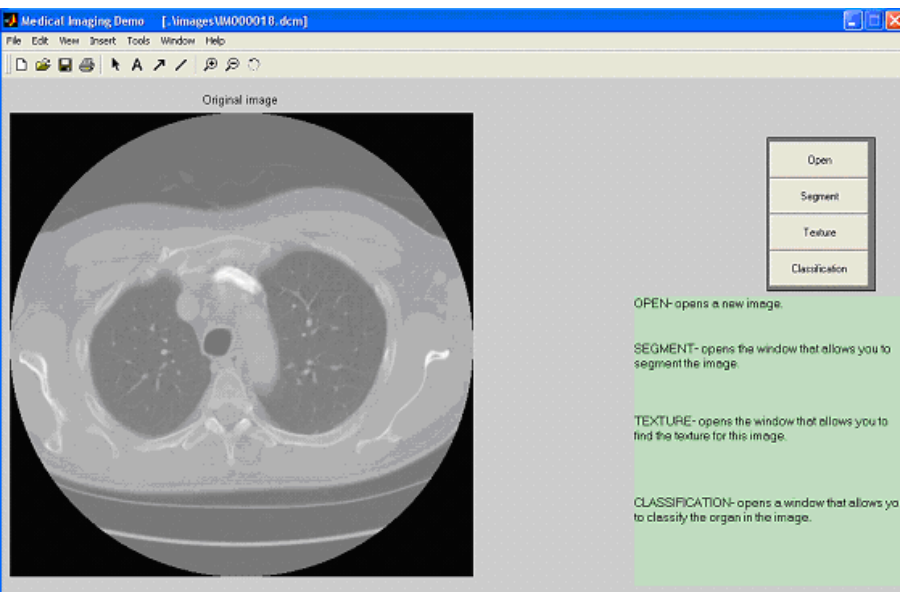


Segmentation



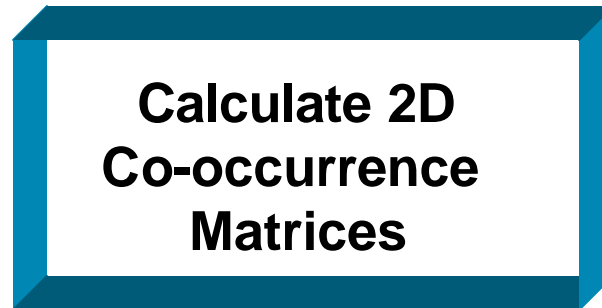
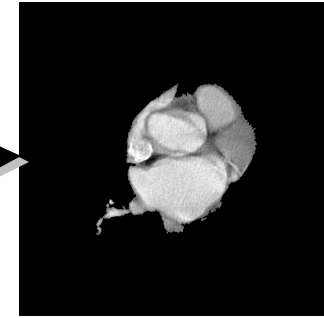
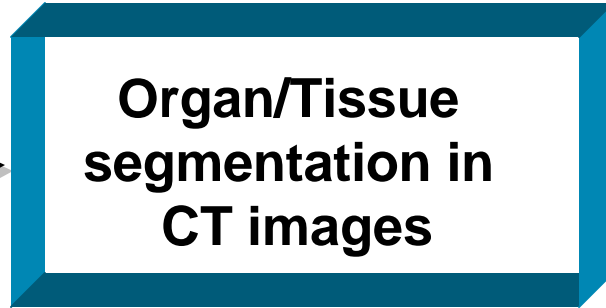
- **Data:** 344 DICOM images
- **Segmented organs:** liver, kidneys, spleen, backbone, & heart
- **Segmentation algorithm:** *Active Contour Mappings (Snakes)*
 - A boundary-based segmentation algorithm
 - Input for the algorithm: a number of initial points & five main parameters that influence the way the boundary is formed
 - The values of the five parameters simulate the action of two forces:
 - Internal: designed to keep the snake smooth during the deformation
 - External: designed to move the snake towards the boundary

Segmentation

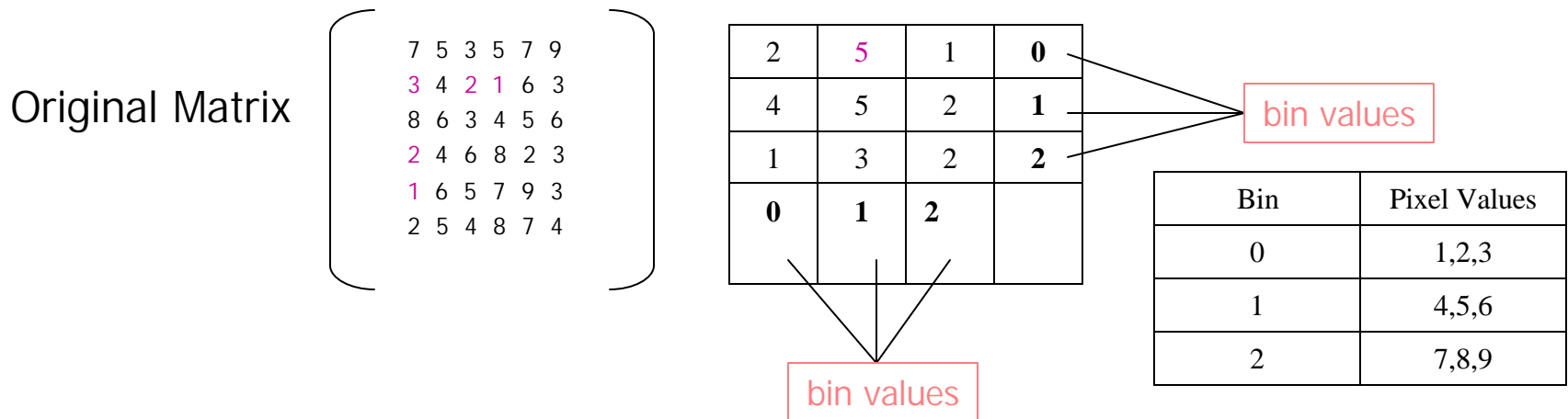


- **What is texture?**
 - *Texture* is a measure of the variation of the intensity of a surface, quantifying properties such as smoothness, coarseness, and regularity
 - *Texture* is a connected set of pixels satisfying a given gray level property which occurs repeatedly in an image region constitutes a textured region
- **Texture Models:**
 - Co-occurrence Matrices
 - Run-Length Matrices

Co-occurrence Matrices



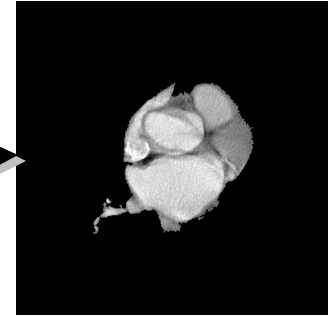
- **2D Co-occurrence Matrix (Haralick 1973)**
 - Capture the spatial dependence of gray-level values within an image
 - A 2D co-occurrence matrix, P , is an $n \times n$ matrix, where n is the number of gray-levels within an image
 - The matrix acts as an accumulator so that $P[i, j]$ counts the number of pixel pairs having the intensities i and j



Feature Extraction



Organ/Tissue segmentation in CT images



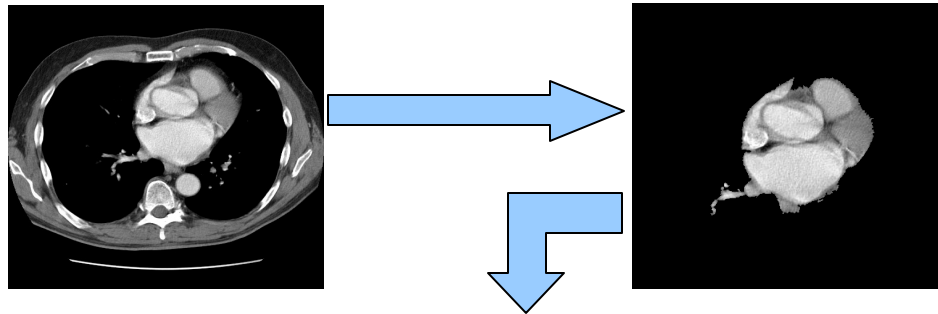
Calculate 2D Co-occurrence Matrices

Calculate numerical texture descriptors for each region
 $[D_1, D_2, \dots, D_{10}]$

- **2D Co-occurrence Matrix (cont.)**
- In order to quantify this spatial dependence of gray-level values, we calculate various textural features proposed by Haralick:
 - Entropy
 - Energy (Angular Second Moment)
 - Contrast
 - Homogeneity
 - SumMean (Mean)
 - Variance
 - Correlation
 - Maximum Probability
 - Inverse Difference Moment
 - Cluster Tendency

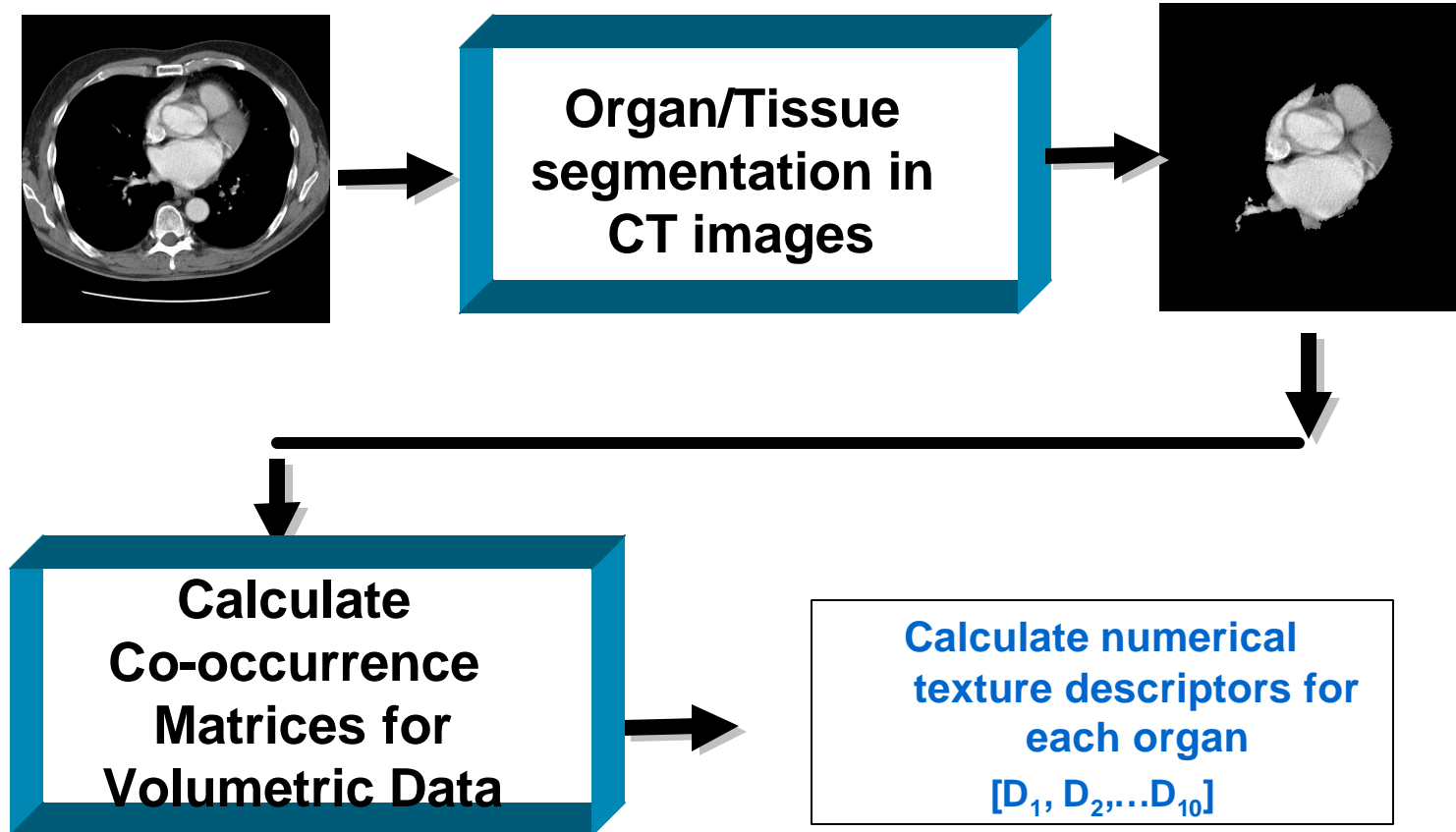
2D Results

- For each slice per organ we average the feature values derived from the 20 matrices, leaving us with a single value per feature per slice:



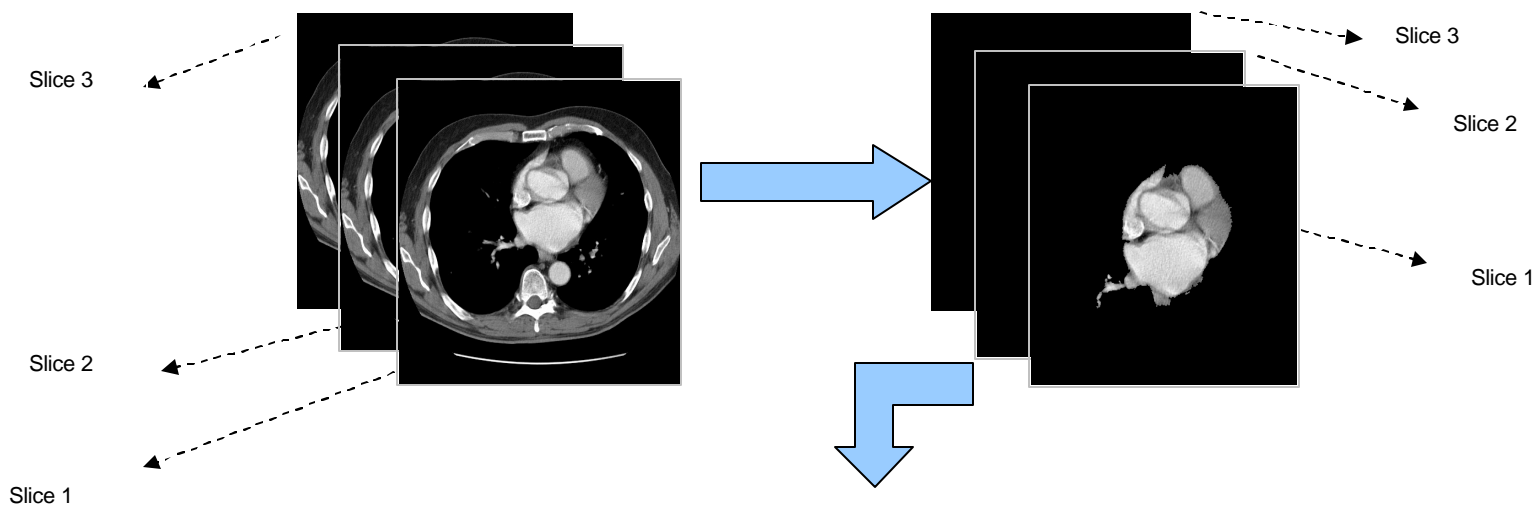
Entropy	Energy	Contrast	Homogeneity	SumMean	Variance	Correlation	Maximum Probability	Inverse Difference Moment	Cluster Tendency
3.892828	.034692	2.764427	.6345745	11.662886	7.308909	.110921	.112929	.44697	26.471211

Feature Extraction



Volumetric Results

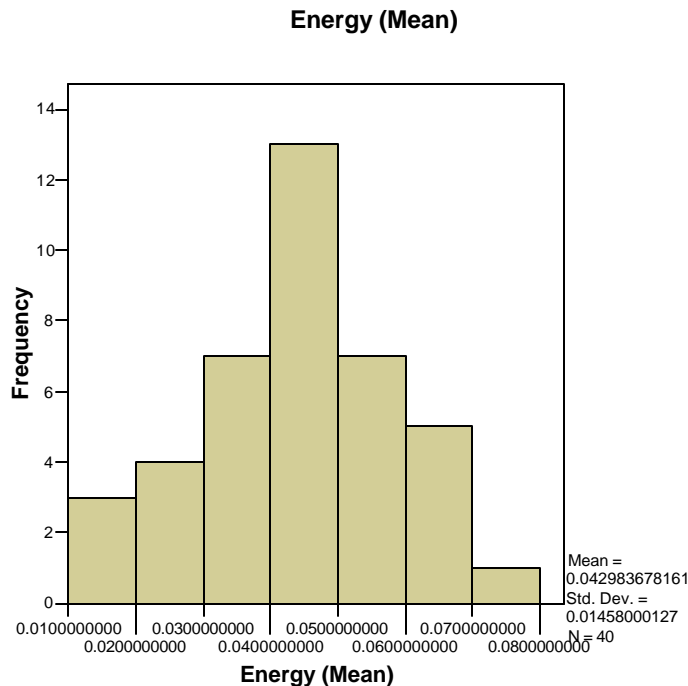
2D dependence matrices that are able to capture the spatial dependence of gray-level values in a set of three-dimensional data (i.e. a set of CT scans for a given patient = single 3D input)



Entropy	Energy	Contrast	Homogeneity	SumMean	Variance	Correlation	Maximum Probability	Inverse Difference Moment	Cluster Tendency
3.80848	0.03709	4.93375	0.54080079	11.07523	3.98559	0.0986871	0.096027	0.4021295	11.008588

3D Results - Backbone

- For each organ, we took the corresponding average feature value and plotted it on the 2D graph (does it fall within min and max?):
- Using the five number summary for 2D data, we defined another range (does the volumetric value fall within Q1 and Q3?):



		Energy (Mean)
Minimum		0.01230
Maximum		0.07021
Percentiles	25.00000	0.03211
	50.00000	0.04226
	75.00000	0.05375

Volumetric Data

Patient 1 - 0.03295

Patient 2 - 0.03746

2D and 3D Results

The distribution of the volumetric co-occurrence descriptors with respect to the 2D data

	# of Organs	$Q_1 - Q_3$	Min - Max
Entropy	5	2	5
Energy	5	2	5
Contrast	5	1	3
Homogeneity	5	1	3
SumMean	5	4	5
Variance	5	5	5
Correlation	5	2	4
Maximum Probability	5	2	5
Inverse Difference Moment	5	1	3
Cluster Tendency	5	5	5
TOTAL	50	25	43

2D and 3D Results

The distribution of the volumetric co-occurrence descriptors per organ

	# of Desc.	$Q_1 - Q_3$	Min - Max
Backbone	10	4	10
Heart	10	4	7
Kidney	10	3	6
Liver	10	8	10
Spleen	10	6	10
TOTAL	50	25	43

Run-length encoding

- Run-length encoding is used to represent strings of symbols in an image matrix
- For a given image *a gray level run* is defined as a set of consecutive, collinear pixels having the same gray level
- *Length of the run* is the number of pixels in the run

0000111100111

- Galloway proposed the use of a run-length matrix for texture feature extraction
- Run-length statistics capture the coarseness of a texture in a specific direction

Definition of Run-Length Matrices

The run-length matrix $p(i, j)$ is defined by specifying direction and then count the occurrence of runs for each gray levels and length in this direction

- (i) Dimension corresponds to the gray level (bin values) and has a length equal to the maximum gray level (bin values) n
- (j) dimension corresponds to the run length and has length equal to the maximum run length (bin values)

0°

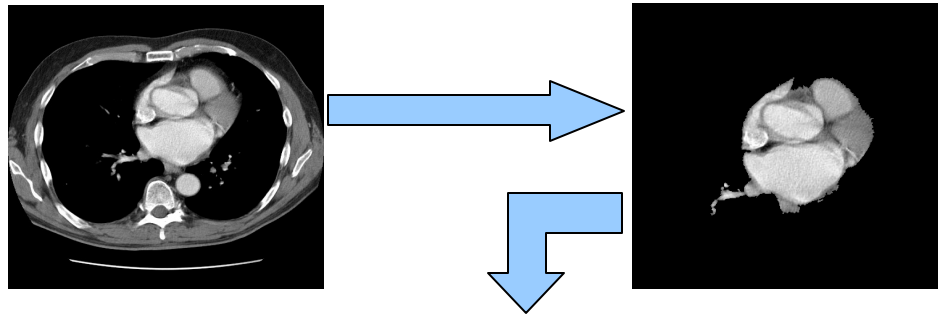
1	1	2	1	1
3	3	1	1	2
1	1	2	3	1
3	1	2	2	1
1	1	3	2	2
2	3	1	1	2

$i \backslash j$	1	2	3	4	5	6
1	1	8	0	0	0	0
2	2	4	1	0	0	0
3	4	1	0	0	0	0

- **Run-length matrix (cont.)**
- Eleven texture descriptors are calculated to capture the texture properties and differentiate among different textures
 - short run emphasis (SRE)
 - long run emphasis (LRE)
 - high gray-level run emphasis (HGRE)
 - low gray-level run emphasis (LGRE)
 - Short Run Low Gray-Level Emphasis (SRLGE)
 - Short Run High Gray-Level Emphasis (SRHGE)
 - Long Run Low Gray-Level Emphasis (LRLGE)
 - Long Run High Gray-Level Emphasis (HRHGE)
 - Gray-Level Non-uniformity (GLNU)
 - Run Length Non-uniformity (RLNU)
 - Run Percentage (RPC)

2D Results

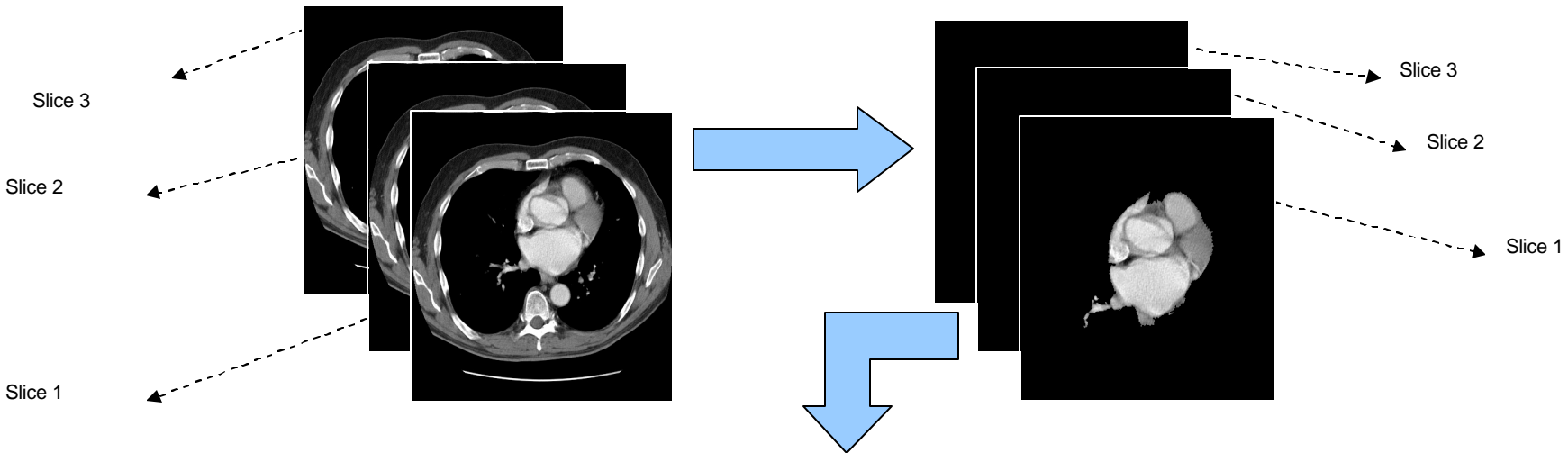
- For each slice per organ we calculated the feature values derived from the four matrices, leaving us with a single value per feature per slice:



<i>SRE</i>	<i>LRE</i>	<i>LGRE</i>	<i>HGRE</i>	<i>SRLGE</i>	
0.7946625	1.9866925	0.0049275	209.80237	0.00399	
<i>SRHGE</i>	<i>LRHGE</i>	<i>LRLGE</i>	<i>GLNU</i>	<i>RLNU</i>	<i>RPC</i>
163.619125	434.95482	0.0093575	218.6210575	584.8621275	0.769425

Volumetric Results

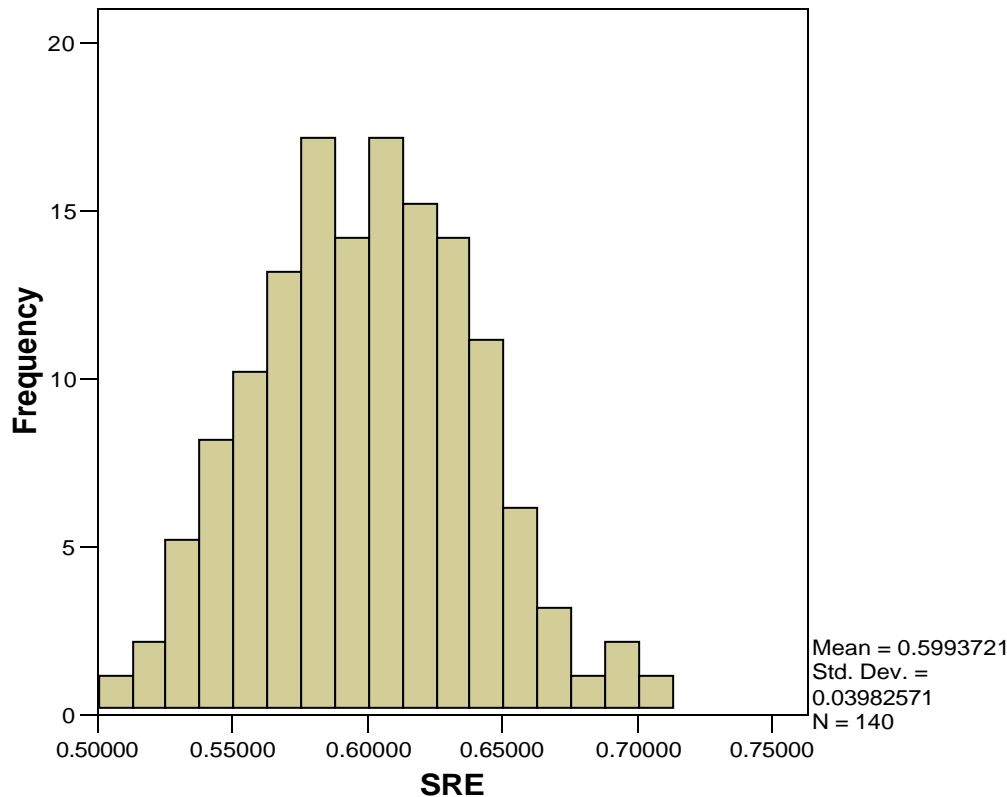
2D dependence matrices that are able to capture the spatial dependence of gray-level values in a set of three-dimensional data (i.e. a set of CT scans for a given patient = single 3D input)



SRE	LRE	LGRE	HGRE	SRLGE	
0.7946625	1.9866925	0.0049275	209.80237	0.00399	
SRHGE	LRHGE	LRLGE	GLNU	RLNU	RPC
163.619125	434.95482	0.0093575	218.6210575	584.8621275	0.769425

- For each organ, we took the corresponding average feature value and plotted it on the 2D graph
- Using the five number summary for 2D data, we defined another range

Histogram



Minimum		0.50515
Maximum		0.71057
percentile	25	0.57065
	50	0.60013
	75	0.62919

Backbone SRE

- The distribution of the volumetric run-length descriptors with respect to the 2D data

	# of Organs	Q1-Q3	Min-Max
sre	5	0	0
lre	5	1	3
lgre	5	5	5
hgre	5	5	5
srlge	5	0	4
srhge	5	2	3
lrhge	5	1	2
lrlge	5	1	2
rpc	5	0	2
total	45	15	26

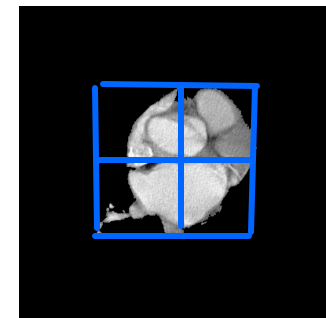
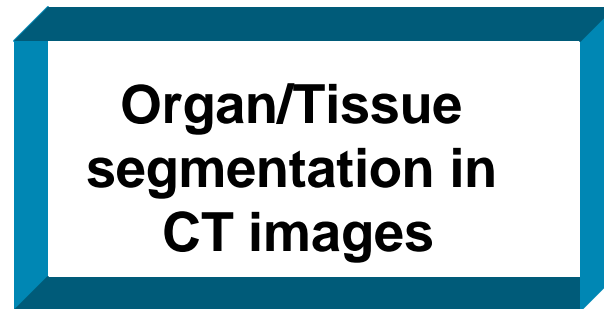
- The distribution of the volumetric run-length descriptors per organ

	# of Desc.	Q1-Q3	Min-Max
backbone	9	3	5
heart	9	2	6
kidney	9	2	2
liver	9	6	8
spleen	9	2	5
total	45	15	26

- **Motivation:**

Investigate the feasibility of automated classification of human organ tissues in a chest and abdominal CT image

- **Stage 1: Texture feature extraction**



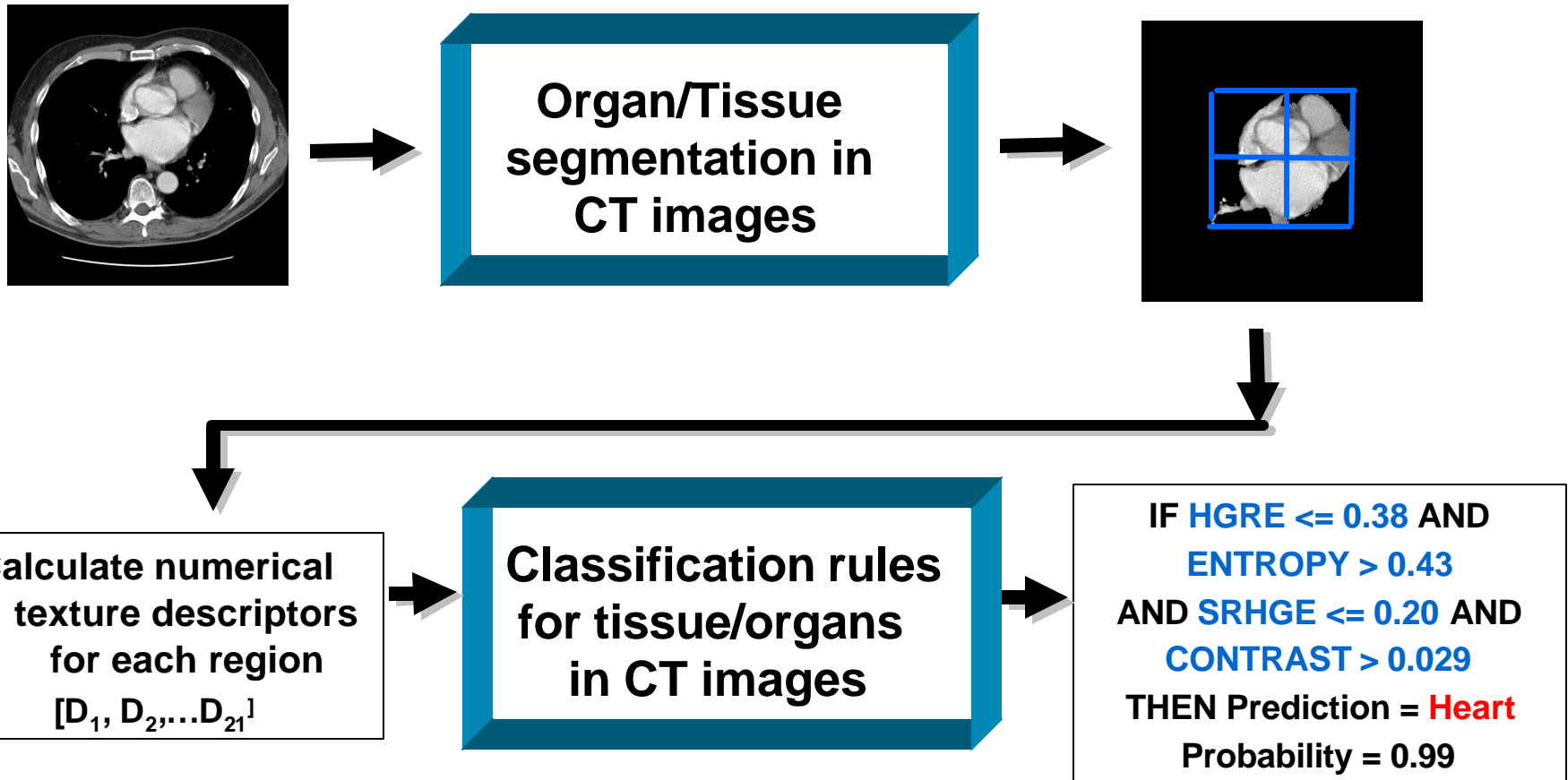
**Calculate numerical
texture descriptors
for each region**
 $[D_1, D_2, \dots, D_{21}]$

Data: $340 \times 4 = 1360$ regions of interests

Segmented organs: liver, kidneys, spleen,
backbone, & heart

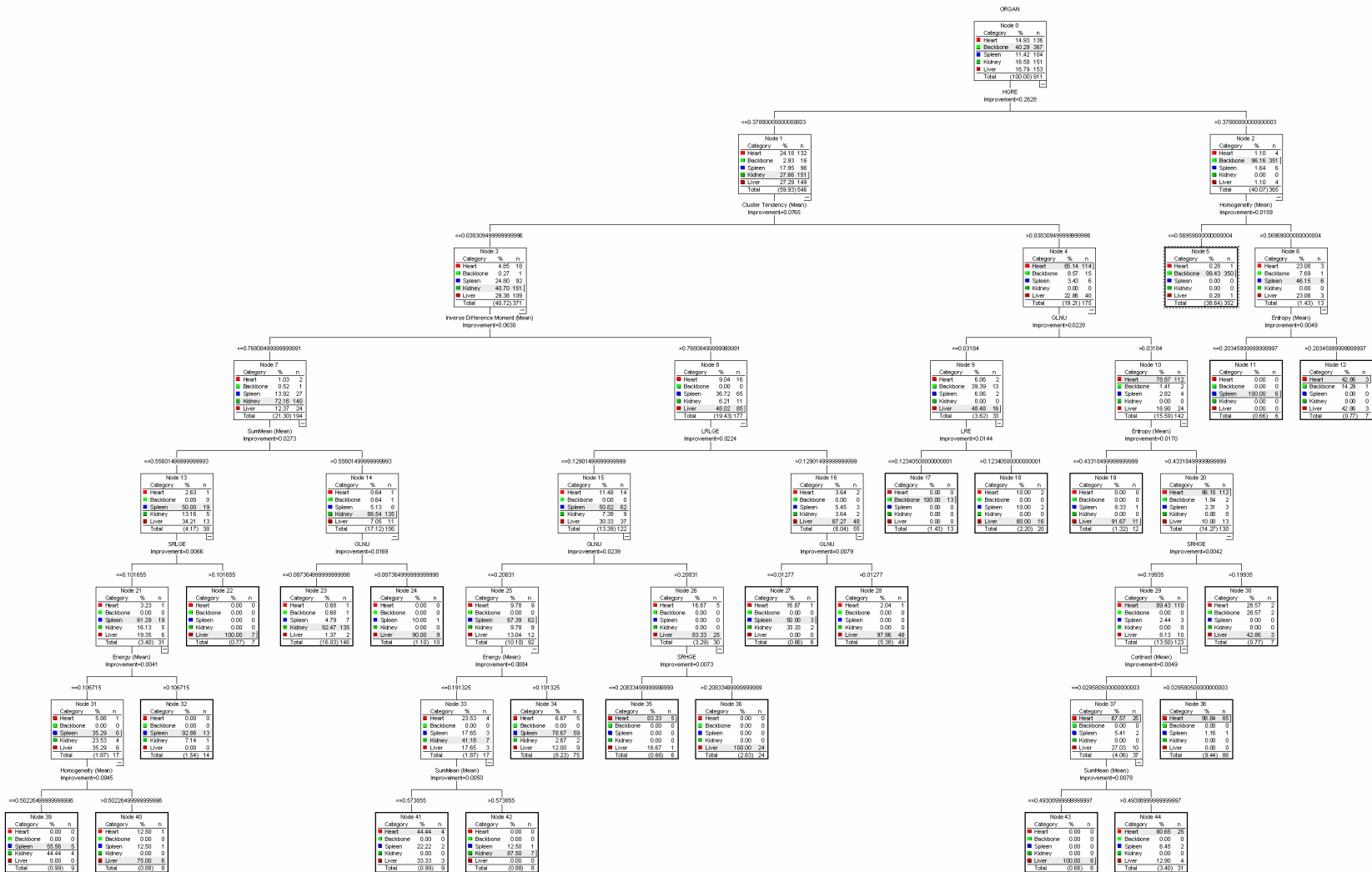
Stage 2: Classifier creation

Data: 911 training set (66.6%), 449 testing set (33.3%)



Classifier Creation

Decision Tree: A decision tree is a flow-chat-like structure that resembles a tree



- **Decision rules** highlight the most relevant descriptors for the classification of chest and abdominal image

```
IF ((HGRE <= 0.3788) AND  
    (CLUSTER > 0.0383095 ) AND  
    (GLNU <= 0.03184) AND  
    (LRE <= 0.123405))
```

THEN

Node = 17

Prediction = Backbone

Probability = 1.000000

- Classification accuracy parameters
 - sensitivity
 - specificity
 - precision
 - accuracy

Organ/Tissue Classification

Decision Tree Accuracy on Testing Data

(Co-occurrence, Run-length, and Combined):

ORGAN	Sensitivity	Specificity	Precision	Accuracy
Backbone	96% / 98% / 98%	99% / 100% / 99%	99% / 99% / 99%	98% / 99% / 99%
Liver	64% / 57% / 78%	96% / 98% / 95%	75% / 84% / 71%	92% / 92% / 92%
Heart	79% / 82% / 75%	96% / 95% / 98%	80% / 77% / 90%	94% / 93% / 95%
Kidney	89% / 89% / 89%	96% / 93% / 96%	80% / 67% / 77%	94% / 92% / 95%
Spleen	60% / 44% / 60%	93% / 93% / 95%	53% / 45% / 63%	89% / 87% / 91%

- **Conclusion**

- Using only 21 descriptors it is possible to classify different organ tissues in the CT images
- Combining some other texture models will increase the performance of the classifier

- **Future Work**

- Improve snake segmentation
- Compare the classification result with result obtained using neural network technique
- Use texture descriptors derived from volumetric data to aid the classification in CT image